

# RIEGL VUX-SYS<sup>®</sup>

- *complete miniaturized ALS System*
- *RIEGL VUX-1 lightweight airborne laser scanner integrated*
- *inertial measurement unit and GPS/GLONASS receiver integrated*
- *compact control unit with various interfacing options*
- *various mounting options for highly flexible aircraft installation*
- *prepared for remote control via low-bandwidth data link*
- *operates up to 4 digital cameras*

The *RIEGL VUX-SYS* is a complete on-board airborne laser scanning system of low weight and compact size for flexible use in UAS/UAV/RPAS, helicopter, gyrocopter and ultra-light aircraft installations.

The system comprises the *RIEGL VUX-1* airborne laser scanner, an IMU/GNSS system and a dedicated control unit. The excellent measurement performance of the VUX-1 in combination with the precise inertial measurement unit and the associated GPS/GLONASS receiver results in survey-grade measurement accuracy over its full range of applications.

The VUX-SYS is specifically designed to be easily installed or exchanged by the user, alternatively either in the *RIEGL VP-1* helicopter pod, the *RIEGL RiCOPTER* unmanned aerial system, or in any mobile measuring system, whatsoever.

The VUX-SYS is complemented within the VP-1 by one single high resolution digital camera, and in the *RiCOPTER* by two lightweight consumer-grade digital cameras. It is prepared to handle up to 4 independent cameras in other installations.

The small size, low weight, and small number of interconnecting cables required accounts for a very short set-up time of the system.

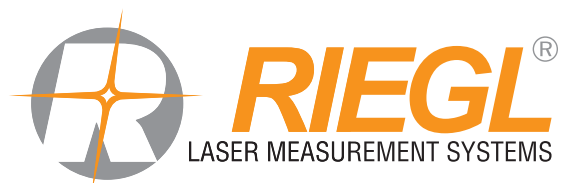
The VUX-SYS is delivered with the necessary software tools for processing scan data as well as IMU/GNSS data.

Based on the software bundle RiPROCESS and its associated software tools, scan data is geo-referenced, calibrated and exported fully automatically.

#### Typical applications include

- *Corridor Mapping: Power Line, Railway Track, and Pipeline Inspection*
- *Terrain and Canyon Mapping*
- *Surveying of Urban Environments*
- *Topography in Open-Cast Mining*
- *Precision Agriculture*
- *Archaeology and Cultural Heritage Documentation*
- *Construction-Site Monitoring*

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## RIEGL VUX®-SYS for RiCOPTER

The VUX-SYS fits the dedicated mounting bay of the RiCOPTER directly without any adaptations. The system is supplemented by two digital cameras, covering a field of view of approximately 160 degrees. The low weight of the VUX-SYS enables the RiCOPTER to operate for about half an hour at a gross weight of 25kg.



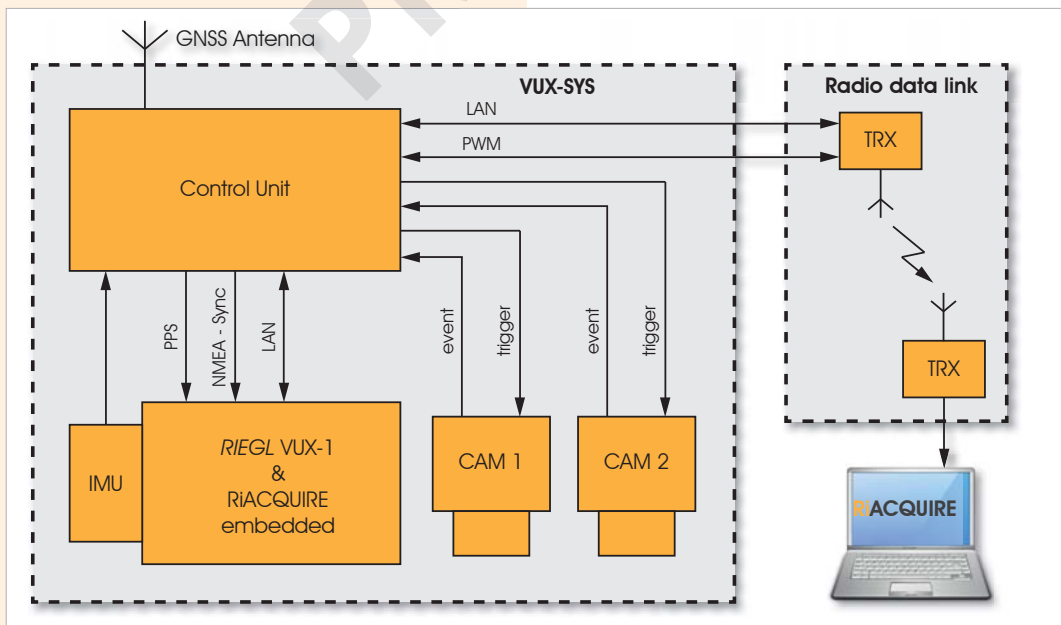
### RIEGL VUX-SYS for RiCOPTER System Components:

- RIEGL VUX-1 UAS LiDAR sensor
- IMU/GNSS unit (Applanix AP20)
- GNSS antenna
- Control Unit
- 2 cameras (SONY alpha 6000)
- connecting cables

## RIEGL VUX®-SYS - Block Diagram Remote Control Setup

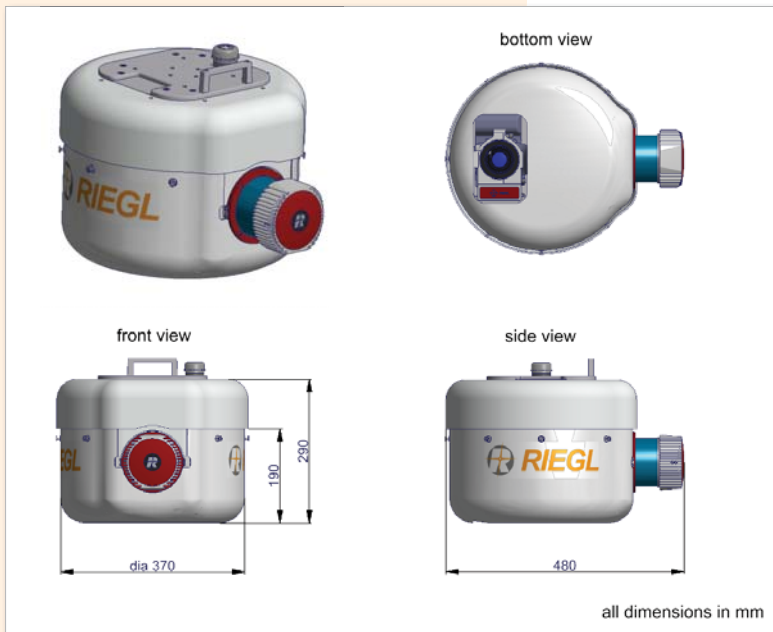
Accounting for the integration in unmanned remotely piloted systems, a dedicated TTL interface for receiving and emitting **Pulse-Width Modulated (PWM)** signals enables full control as well as system status feedback. Based on a predefined set of commands and associated pulse widths the system can be controlled easily via a standard remote-control radio channel of low bandwidth.

It is possible to adjust the data rate of scan data for streaming monitoring data even in real-time via suitable radio channels of sufficient bandwidth.



## RIEGL VUX®-SYS for VP-1

The VUX-SYS fits the small and lightweight RIEGL VP-1 pod, to be mounted on standard hard points and typical camera mounts of manned helicopters. Quick release adapter brackets and a minimum of external cabling (i.e. power supply, LAN, GPS antenna) allow quick system installation and removal.



### RIEGL VP-1

#### System Components:

- RIEGL VUX-1 UAS LiDAR sensor
- IMU/GNSS unit (Applanix AP20)
- GNSS antenna
- Control unit
- digital camera (Nikon D810 or Phase One iXU150)
- connecting cables

### RIEGL VP-1

#### Technical Data:

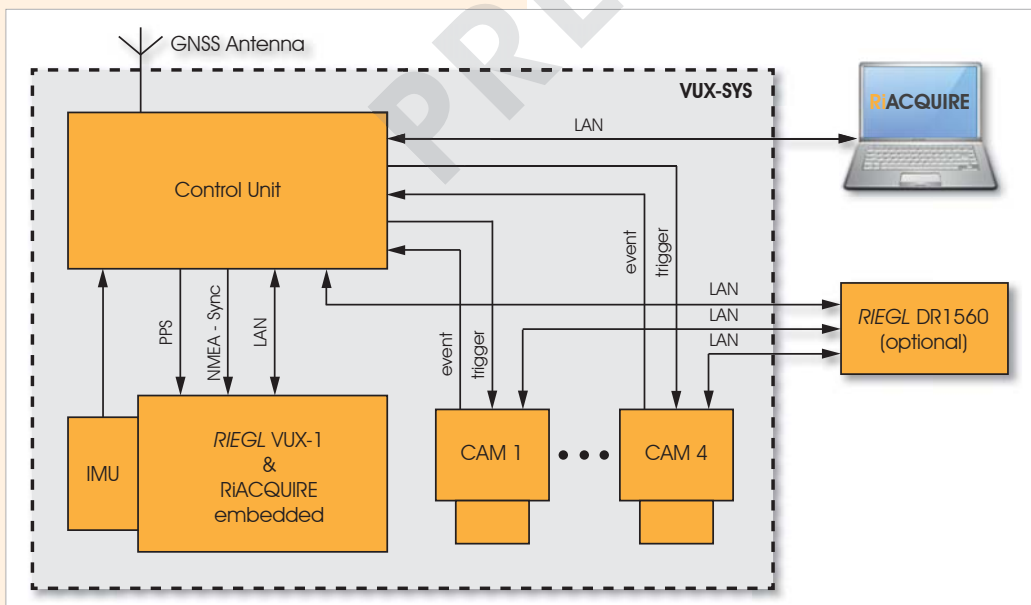
- quick installation & removal using the existing mounts (e.g. AirFILM Camera System); mounting and operation at enduser's responsibility
- total weight approx. 19 kg
- area exposed to wind 0.114 m<sup>2</sup>

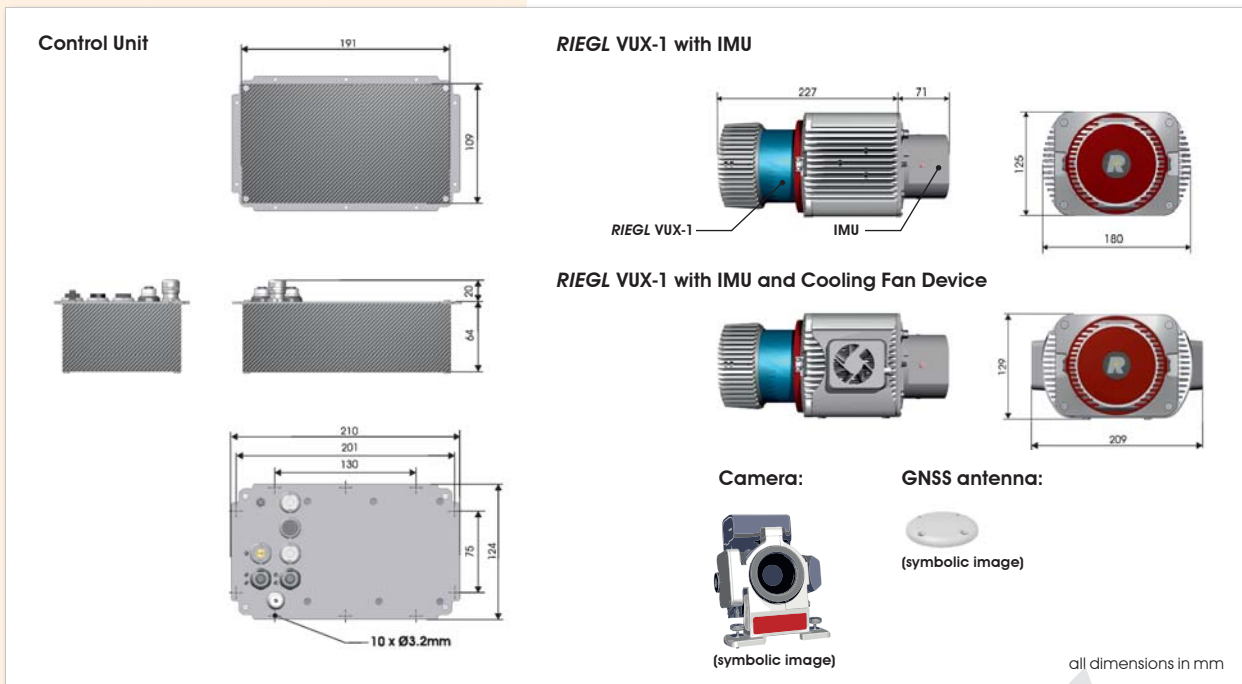
## RIEGL VUX®-SYS - Block Diagram Conventional Control Setup

The VUX-SYS contains a LAN interface for direct control from an operator's working station running RiACQUIRE. RiACQUIRE is fully compatible with the VUX-SYS and enables full control over the laser scanner, the IMU/GNSS system, and optionally up to 4 digital cameras.

Scan data and image data can be directly stored on the particular sensor's internal storage, or can be directly stored on an optional data recorder DR1560 or on a Laptop.

The control unit contains trigger and event marker interfaces for each camera. Precise time stamps of the camera's release-events are stored in the raw scan data stream enabling combination of point cloud data and imagery in subsequent data processing.





## Technical Data RIEGL VUX®-SYS

### Scanner Performance (for details refer to the VUX-1 data sheet)

|   |  |
|---|--|
| Maximum Range (natural targets $\rho \geq 20\%$ ) | 550 m  |
| Minimum Range                                     | 3 m  |
| Accuracy  | 10 mm  |
| Precision   | 5 mm   |
| Laser Pulse Repetition Rate                       | up to 550 kHz  |
| Max. Effective Measurement Rate                   | up to 500 000 meas./sec. (@ 550 kHz PRR & 330° FOV)              |
| Scanning Mechanism                                | rotating mirror  |
| Field of View (selectable)                        | up to 330° (Note limitations when integrated in RiCOPTER / VP-1) |
| Scan Speed (selectable)                           | 10 - 200 revolutions/sec, equivalent to 10 - 200 scans/sec       |
| Angle Measurement Resolution                      | 0.001°   |

### Data Interfaces

|                  |   |
|------------------|---|
| Configuration    | LAN 10/100/1000 Mbit/sec or TTL PWM   |
| Scan Data Output | LAN 10/100/1000 Mbit/sec or USB 2.0   |
| GNSS Interface   | Serial RS232 interface for data string with GNSS-time information, TTL input for 1PPS synchronization pulse |
| Camera           | 4x trigger and event marker   |

### IMU & GNSS (Applanix AP20)

|                          |                |
|--------------------------|----------------|
| IMU Accuracy             | 0.015°         |
| Roll, Pitch              | 0.035°         |
| Heading                  | 200 Hz         |
| IMU Sampling Rate        | 0.05 m - 0.3 m |
| Position Accuracy (typ.) |                |

### General Technical Data

|  |   |
|--|---|
| Power Supply Input Voltage / Consumption   | 11 - 32 V DC / typ. 72 W (3 A @ 24 V DC)                  |
| Main Dimensions                            |   |
| VUX-1 with IMU, without Cooling Fan Device | 298 x 180 x 125 mm  |
| VUX-1 with IMU and Cooling Fan Device      | 298 x 209 x 129 mm  |
| Control Unit                               | 210 x 124 x 84 mm   |
| Weight (Cabling included)                  |   |
| VUX-1 without / with Cooling Fan Device    | approx. 3.6 kg / approx. 3.85 kg                          |
| Control Unit                               | approx. 0.9 kg  |
| IMU/GNSS (Applanix AP20)                   | approx. 0.7 kg  |
| Camera(s)                                  | depending on selected camera type                         |
| Humidity                                   | max. 80 % non condensing @ 31°C                           |
| Temperature Range                          | 0°C up to +40°C (operation) / -20°C up to +50°C (storage) |



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